



MEASUREMENT OF VERY SMALL ELECTRICAL CAPACITY CHANGES USING BRIDGE METHOD

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Abstract: The main focus of this paper is the practical application of the method for measuring very small changes in capacity at low frequencies. The paper analyzes complete engineering approach to the work of compilation of a workplace, creating a user program, through the optimization of the final engagement of the method for evaluating the results.
Key words: measurement, capacity, very little change, bridge

1. INTRODUCTION

Measurement of very small capacities of organic particles is in practice very difficult and often costly because of the needs of highly sophisticated measuring instruments (Witte, 1993). There is also a need to have very clean and stable environment with minimal noise, vibration, with the requirement for minimum EMI (electromagnetic interference) and high EMS (electromagnetic susceptibility) (Regtien et al., 2004). In this work we focused on measuring very small capacities of inorganic objects (eg metal plates, coins). With a little deeper reflection it is evident that electrical capacitance and inductance are the subject of two properties that are inherently very difficult to be separated. Even an ordinary conductor has a certain capacity, which indicates the ability of wires to collect electrical charge and inductance (determined by magnetic properties of wires).

We often encountered (especially in heavy current electrical engineering) with the need to compensate for the electrical inductance of electrical capacity and vice versa. This is because setting a state of equilibrium in the system, which in practice has resulted in setting the optimum power factor ($\cos \phi$). Again we are at a certain mutual and inseparable scope of these two variables.

In this work we dealt with bridge classical methods, which are in essence very simple (Ferguson, 1933). We use high-precision bridge - LCR meter, which, together with three servo motors controlling the feed to the sensing area of the measuring tip and PC constitute a measuring station. The actuators are controlled displacement of the measuring tip in three axes (x, y, z) and, depending on the shift in the axis will be the LCR meter to measure very small changes in capacitance or inductance L (deformations of springs).

2. USED INSTRUMENTS

Precision LCR meter HP 4284A was used. This instrument provides solution for component and material measurement. It can be used to improve component quality by providing an accurate, high throughput test solution. The wide 20 Hz to 1 MHz test frequency range and superior test signal performance allow testing components to the most commonly used test standards, such as IEC/MIL standards, and under conditions that simulate the intended application.

2.1 LCR meter HP 4284A

Accuracy	0.05 %
Capacitance Range	0.00001 pF - 9.99999 F
Current Range	50 μ A - 20 mArms
Frequency Range	20 Hz - 1 MHz
Impedance Range	0.01 M Ω - 99.9999 M Ω
Voltage Range	5 mV - 2 Vrms

Tab. 1. Some of the properties of LCR meter HP 4284A

2.2 Servomotor C-862 Mercury II

The C-862 Mercury II is the instrument for motion control applications where a precision positioner is to be controlled by a PC or PLC. It features an integrated amplifier and additional TTL I/O capability for flexible automation

In our case, the servo motor is controlled by a set of programmed macroinstructions from PC. Programming environment VEE Pro 9.2 allows us to control the movement of the scanned area towards to measuring tip, speed of movement, the direction of movement (Angus and Hulbert, 2005). In Fig. 1 servo C-862 Mercury II is shown in comparison with the overall view of its size due to the coins.



Fig. 1. C-862 Mercury II

Whole block scheme can be seen in Fig. 2

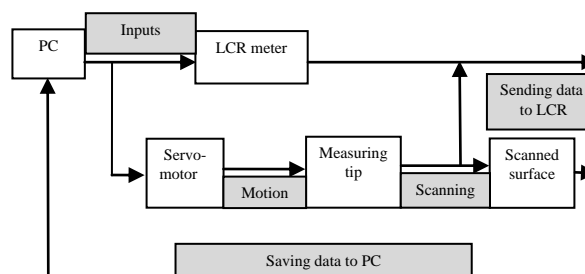


Fig. 2. Block scheme of the measuring system

Inputs – input parameters to instrument (velocity, direction, step, axes).

Motion – servomotor according to input parameters moves the scanned area in given axis (x,y or z).

Scanning – measuring tip connected to static arm measures change in capacity.

Sending data to LCR – changes detected by tip are sent to LCR meter.

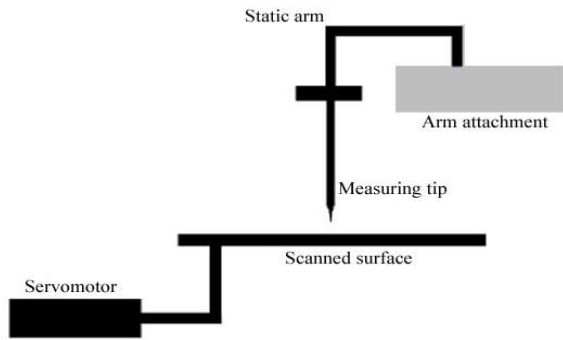


Fig. 3. Electromechanic scheme of the measurement system

Saving data on PC – measured data from LCR meter are stored on PC.

The electromechanic scheme is shown in Fig. 3. The measuring tip is mounted on static arm which is also fastened to the heavy marble slab (due to minimization vibration). The measuring tip itself is static due to moving surface. Appearance of the user application which allows full control of measuring system can be seen in Fig. 4.

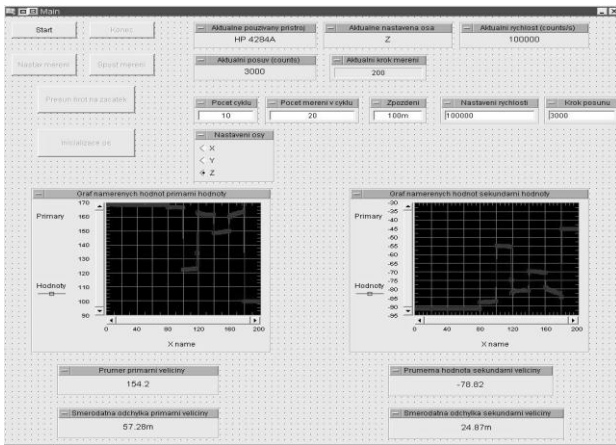


Fig. 4. Control panel of user application in Agilent Vee Pro

3. RESULTS

Dependences of electrical capacity on distance at different frequencies are shown in Fig. 5 and Fig. 6. Parameters of measurement are as follows: d (step) = 18 μm and velocity = 100 000 Counts/s (the same for both dependencies), frequencies = 1 MHz and 100 kHz. The minimal possible change of electrical capacity ΔC_{min} [F] can be determined through derived function of regression curve according measured data – polynomial of degree of three in our case.

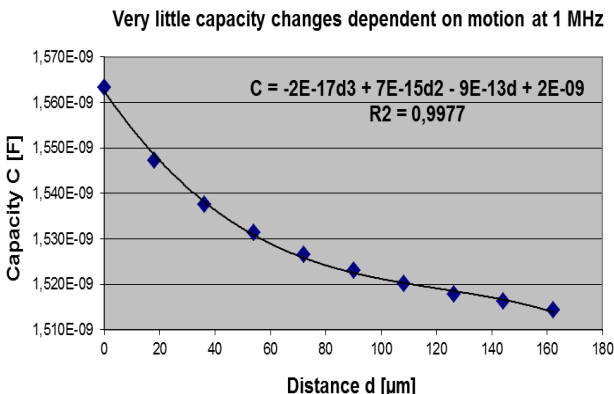


Fig. 5. Electrical capacity measurement at 1 MHz

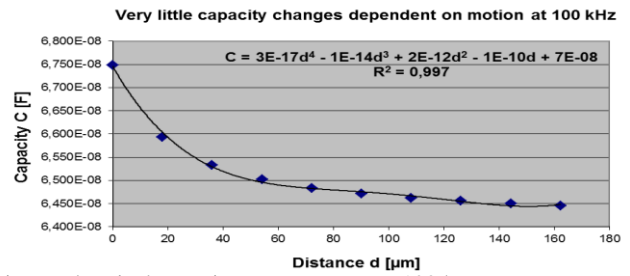


Fig. 6. Electrical capacity measurement at 100 kHz

Polynomial function can be expressed like equation (1). Applying derivative according variable C, we can progressively obtain relations (2) and (3). After final modification and insertion of known values, equation (4) is determined and electrical capacity can be calculated for individual regression coefficients.

$$C = -a_3d^3 + a_2d^2 - a_1d + b \tag{1}$$

$$dC = -a_3dd^3 + a_2dd^2 - a_1dd + b \tag{2}$$

$$\frac{dC}{C} = \frac{-a_3dd^3 + a_2dd^2 - a_1dd + b}{-a_3d^3 + a_2d^2 - a_1d + b} \tag{3}$$

$$\Delta C_{\min} = \frac{-a_3d^2 + a_2d - a_1}{-a_3d + a_2 - a_1 + \frac{b}{d}} \tag{4}$$

4. CONCLUSION

Experimental verification of bridge methods for measuring very small changes in electrical capacity and the gradual optimization showed that the smallest possible changes of electrical capacity ΔC_{min} we are able to achieve at a frequency of 1 MHz, which is the maximal frequency at which the LCR meter can measure. We carried out two types of measurements, - the first one when the surface was moved away from the tip and the second one when the surface approached towards the tip. The best results we achieved at a frequency of 1 MHz. When approaching towards the tip it was ΔC_{min} = 8 nF, when moving away it was ΔC_{min} = 5 nF. At a lower frequency at 100 kHz we achieved minimal changes ΔC_{min} = 26 nF for both directions.

5. ACKNOWLEDGEMENT

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